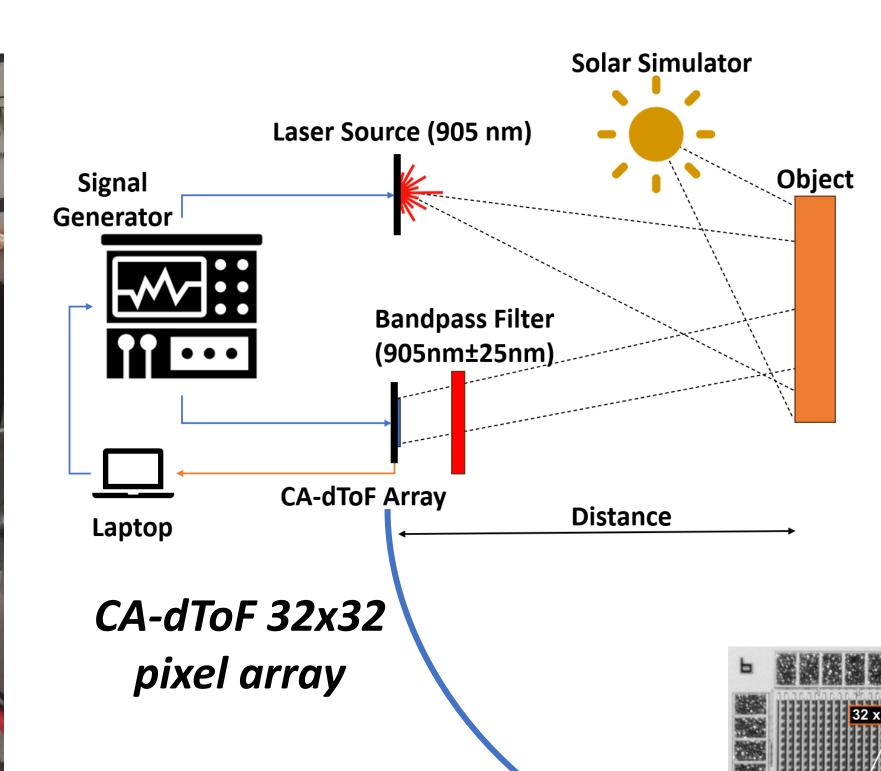
Utilizing Switched Capacitors in a SPAD-Based Pixel for dToF

Ayman Morsy¹, Gobinath Jegannathan*¹, Thomas Lapauw¹, Maarten Kuijk¹ Vrije Universiteit Brussel, Pleinlaan 2, Brussels, Belgium * previous affiliation

The goal is a proof of concept for our SPAD-based dToF camera to suppress ambient light in a pixel.





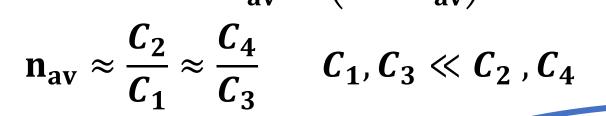
The system is designed to suppress

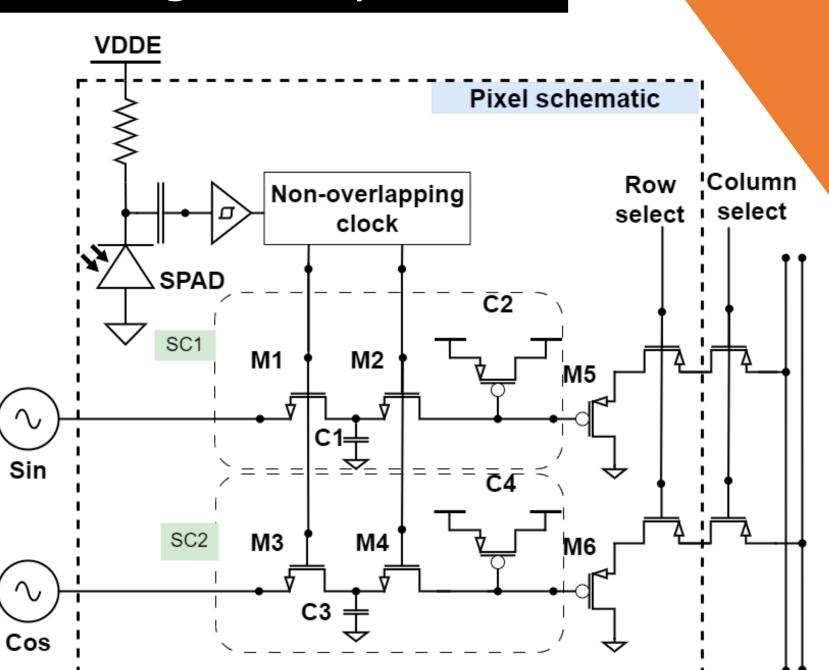
ambient light via in-pixel averaging.

Pixel operation:

- 1) A laser pulse is synchronized with sinusoidal signals.
- When a SPAD is triggered, a non-overlapping signal is generated.
- Sinusoidal voltages "at the time of arrival" are captured and averaged via SC1 and SC2.
- Accumulated voltages evolve via the equation:

$$V_{out}[i+1] = \frac{V_{in}}{n_{av}} + \left(1 - \frac{1}{n_{av}}\right)V_{out}[i]$$





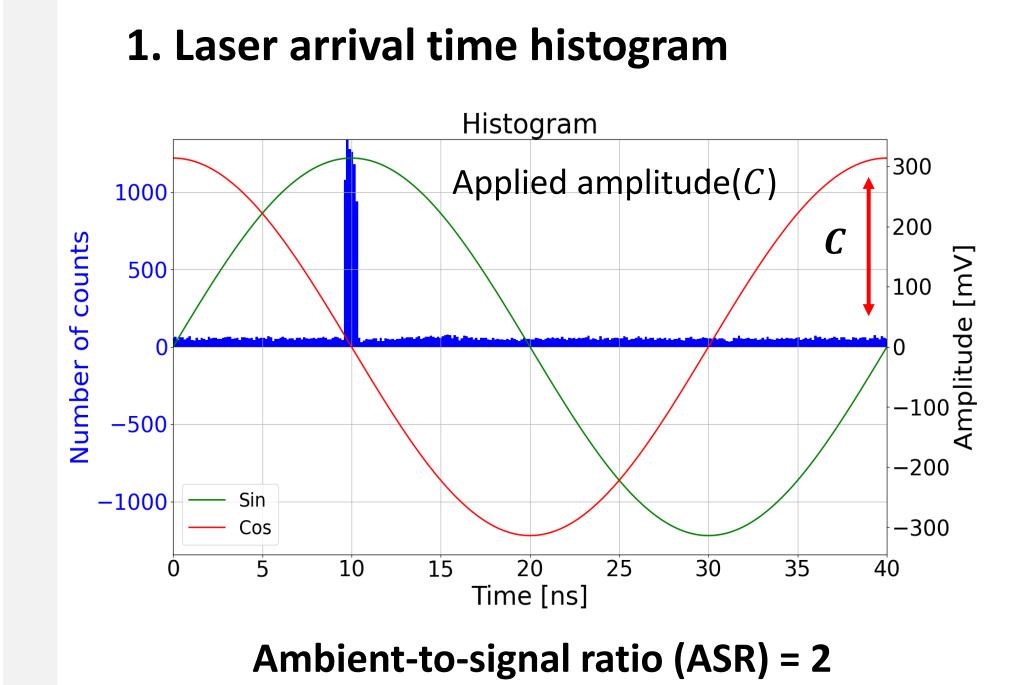
Exponential Weighted Moving Averaging (EWMA):

For a large integration length (n_{av}) , the weight reduction is negligible.

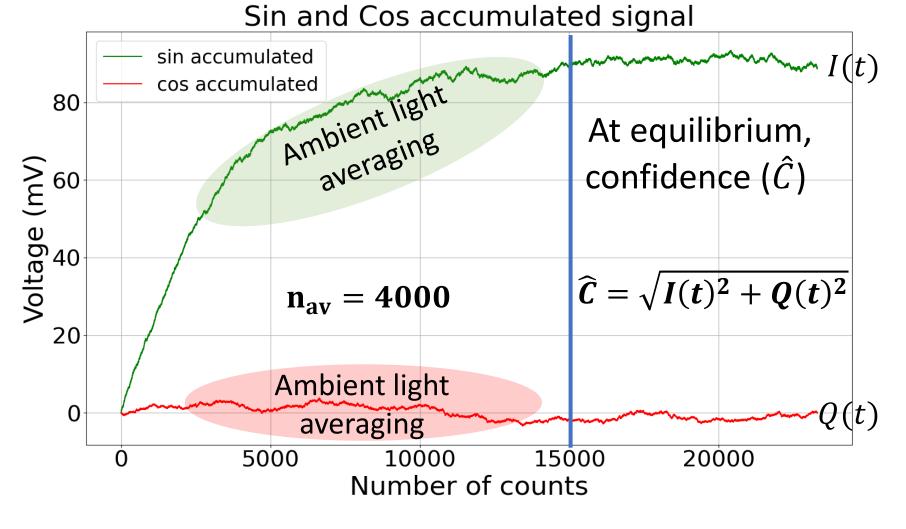
Every measurement has a weight $(w)^{\geq}_{1.5}$ $n_{av} = 300$

For a large (n_{av}) , every new V_{in} is linearly averaged with pervious $V_{out}[i]$.

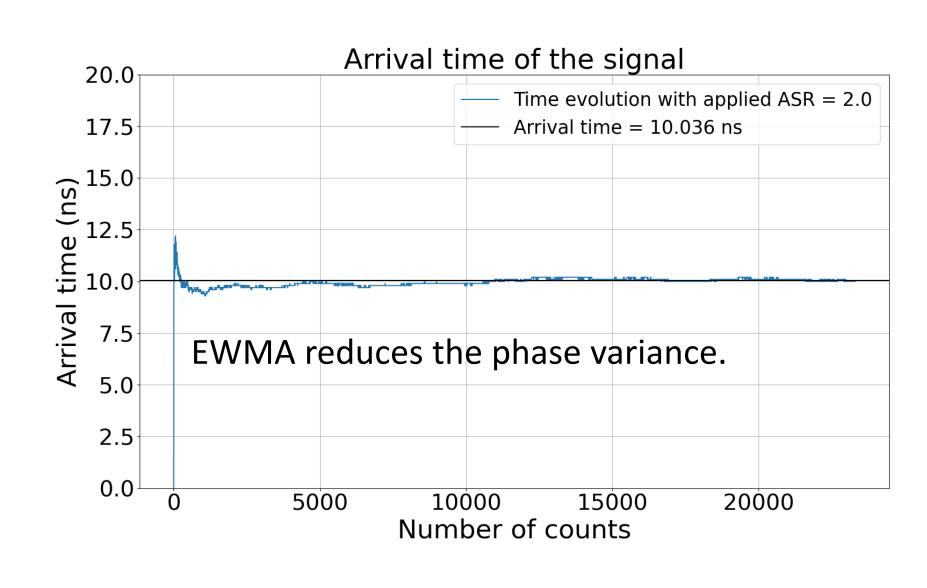
Working Principle







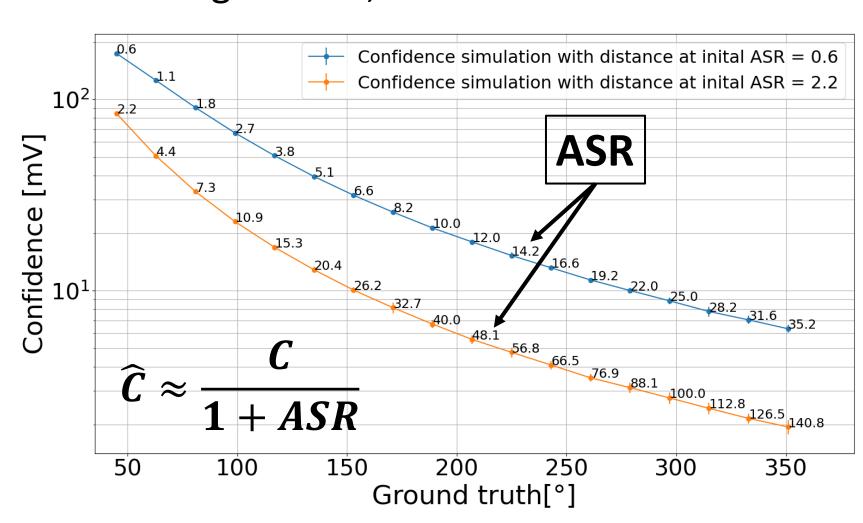
3. Arrival time calculated



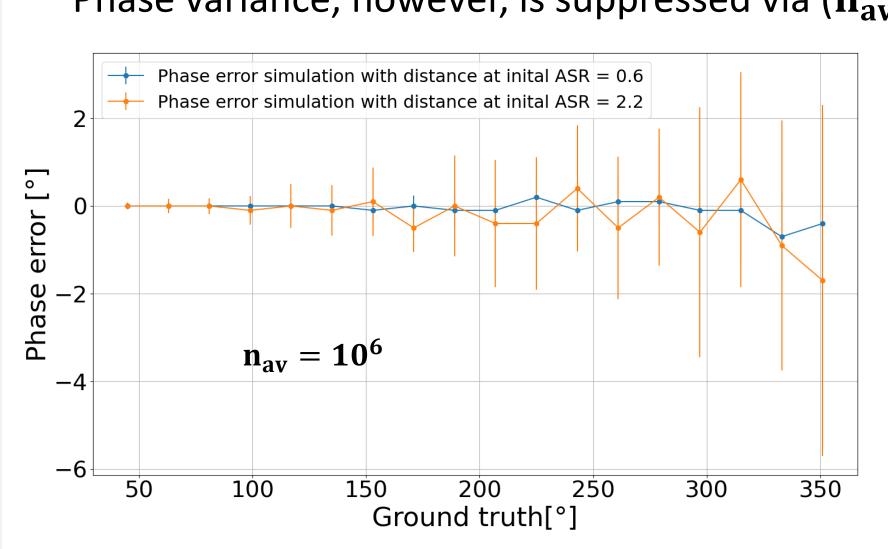
Properties

1) At equilibrium,

the higher ASR, the lower the confidence.

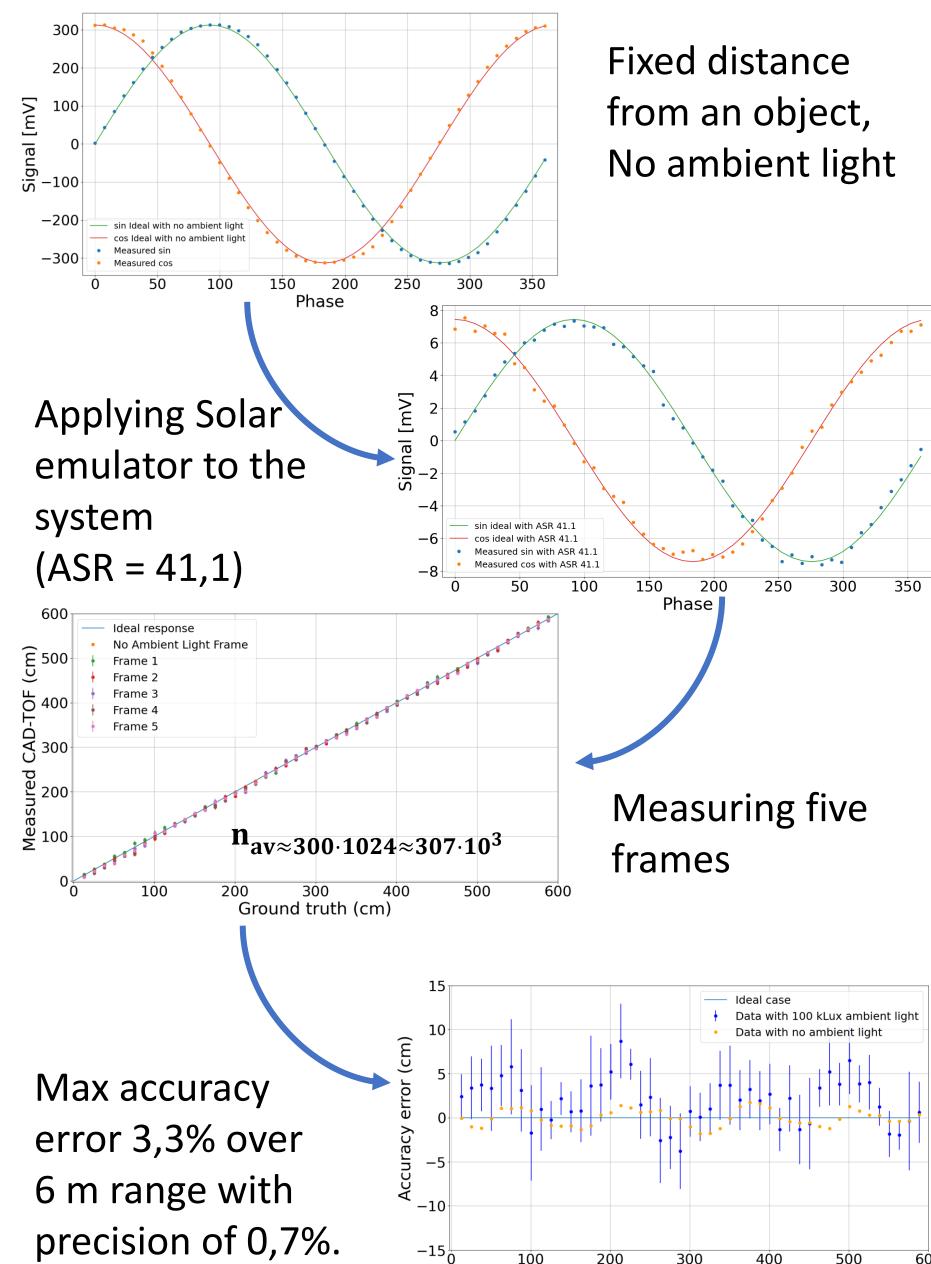


Phase accuracy is minimally influenced by ASR. Phase variance, however, is suppressed via (n_{av})

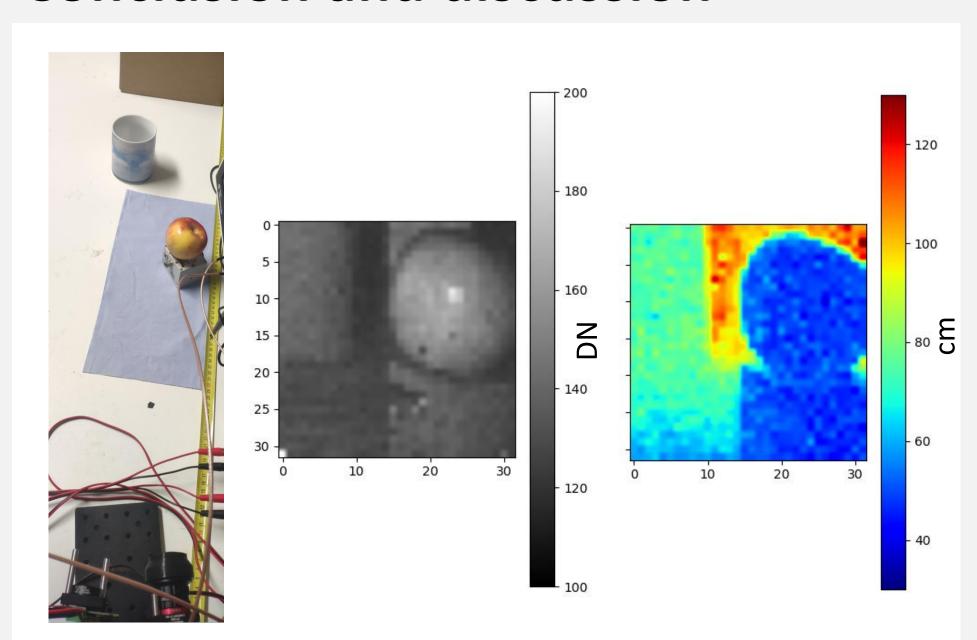


Measurement

For a fixed ASR (Fixed distance of detection)



Conclusion and discussion



- 1. The proposed CA-dToF pixel can suppress ambient light with an in-pixel averaging.
- 2. CA-dToF pixel operation showed consistent results with the statistical simulation.
- 3. Pixel average power consumption was around $40 \ \mu W$, including the SPAD average power.

Upcoming work:

The pixel is challenged by:

- leakage current for smaller technologies,
- and multi-path reflections. SPAD deadtime, •

We are in the process of publishing possible techniques to overcome those challenges.

Ground truth (cm)