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SiPM and SPAD Arrays for Next Generation LiDAR

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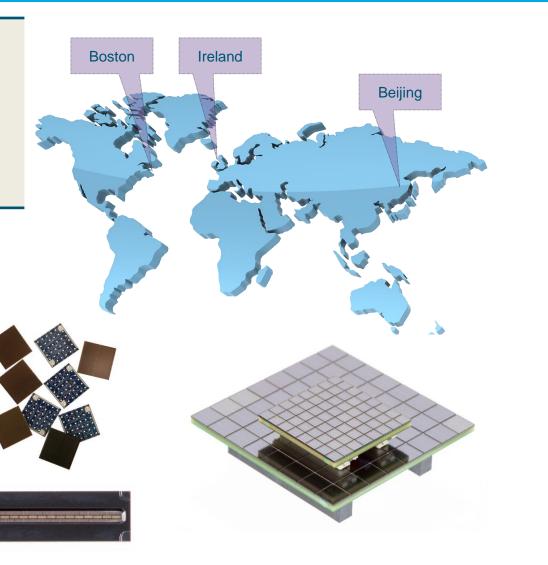
International SPAD-Sensor Workshop

SensL Quick Facts

Business	Low Light Sensors
Markets	Medical Imaging Radiation Detection Automotive LiDAR
Model	Fabless Semiconductor

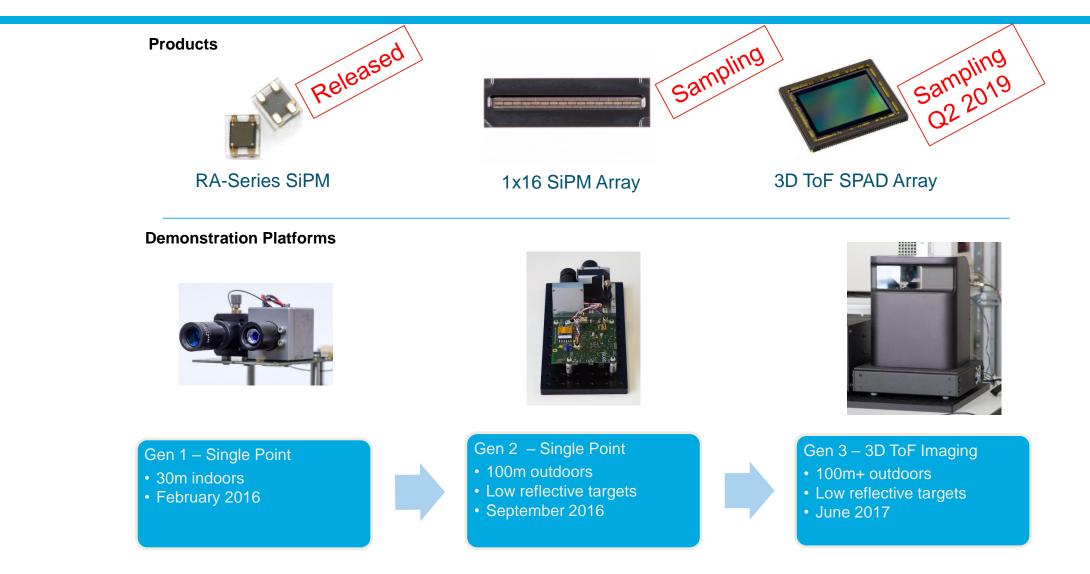
- Established 2004
- ISO9001:2008 Certified







LiDAR Product & Demonstrator Roadmap



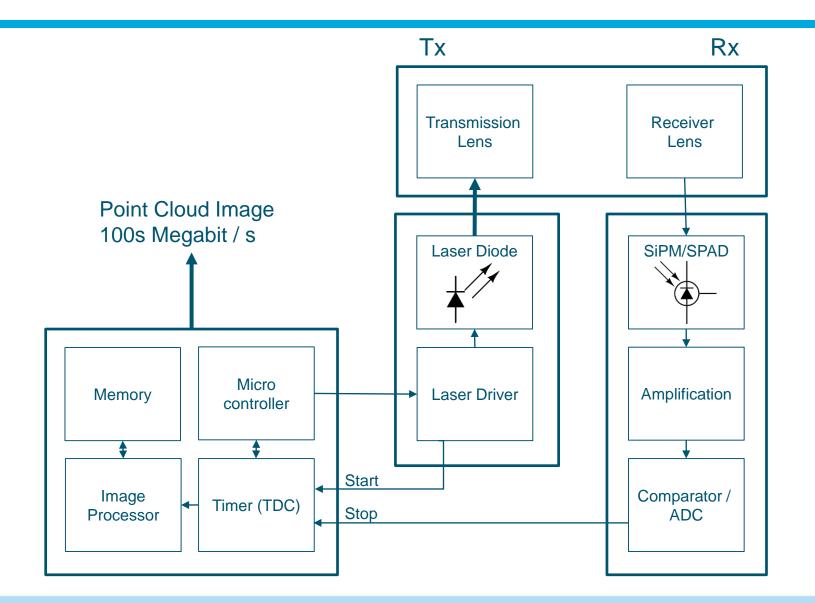


Agenda

- Anatomy of a LiDAR system
 - Tx: eye safe laser beam
 - Rx: high sensitivity SiPM/SPAD sensors
- Challenges for long distance outdoor LiDAR systems
- Current LiDAR systems solutions based on SiPM sensors
- Future LiDAR sensors based on SiPM/SPAD array sensors
- SensL Gen3 demonstrator



Anatomy of a LiDAR System

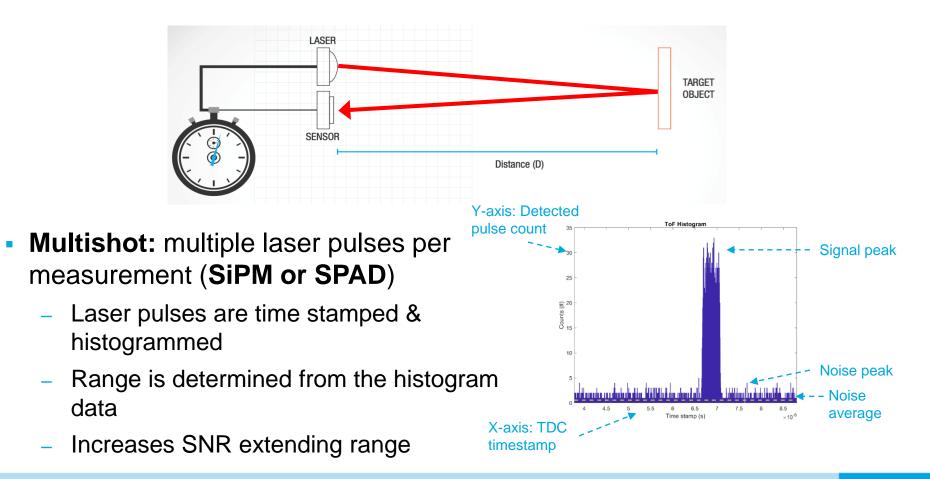




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Direct ToF LiDAR Measurement Techniques

- Single shot: one laser pulse per measurement (SiPM)
 - A single returned pulse is time stamped and the range determined
 - High optical SNR required





Challenges for Long-distance LiDAR Systems

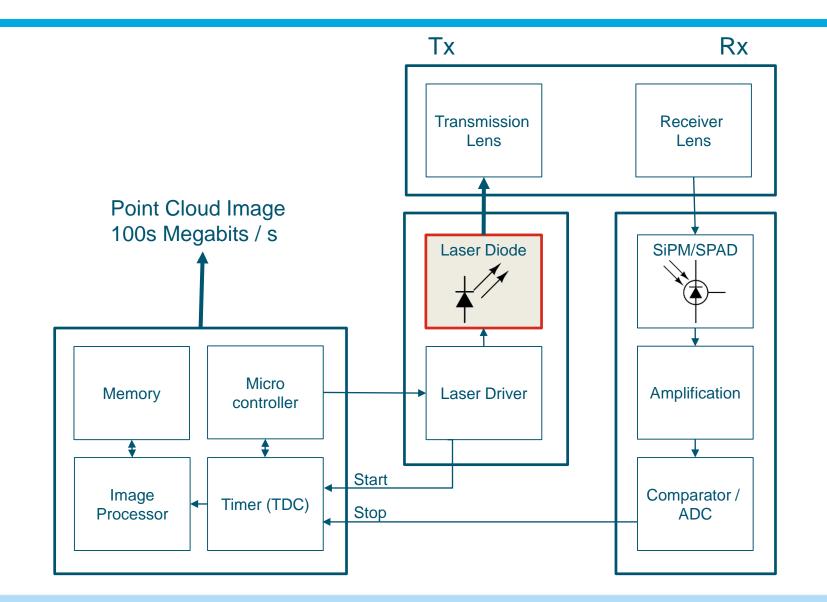
- Tx: Laser diodes / Scanning method
 - High and eye safe laser peak power required for long distance
 - High repetition rate for high frame rate systems
 - Short laser pulses for power optimization
 - Wavelength drift over temperature
 - Allows for narrower bandpass filters to be used and improve ambient rejection
 - Solid-state scanning methods
 - MEMS
 - OPA

Rx: SiPM/SPAD

- High responsivity at 905 nm and 940 nm for long range
- High dynamic range for ambient light rejection
- Compact size cost effective
- High pixelization
 - For high angular resolution
 - For best SNR performance
- High data rate
- Fast read out



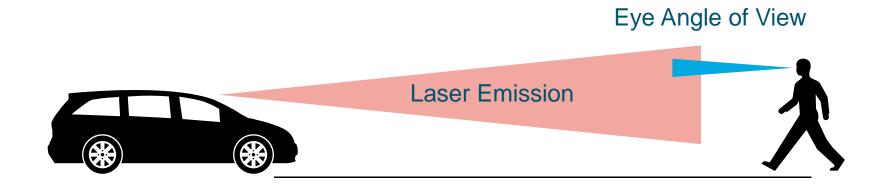
Anatomy of a LiDAR System





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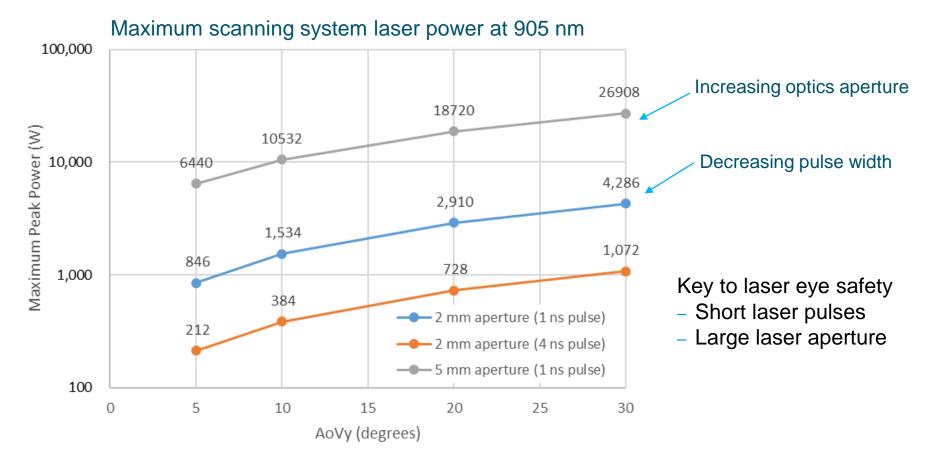
Laser Eye Safety and LiDAR Systems



- Long range LiDAR requires high peak power lasers
- Laser power is spread over a wide angle of view (AoV)
- Aperture of the human eye has a limited AoV
- Important factors to meet eye safety limits from IEC 68025
 - Shorten the laser pulse to reduce energy per pulse
 - Increase the laser aperture for light leaving the LiDAR system



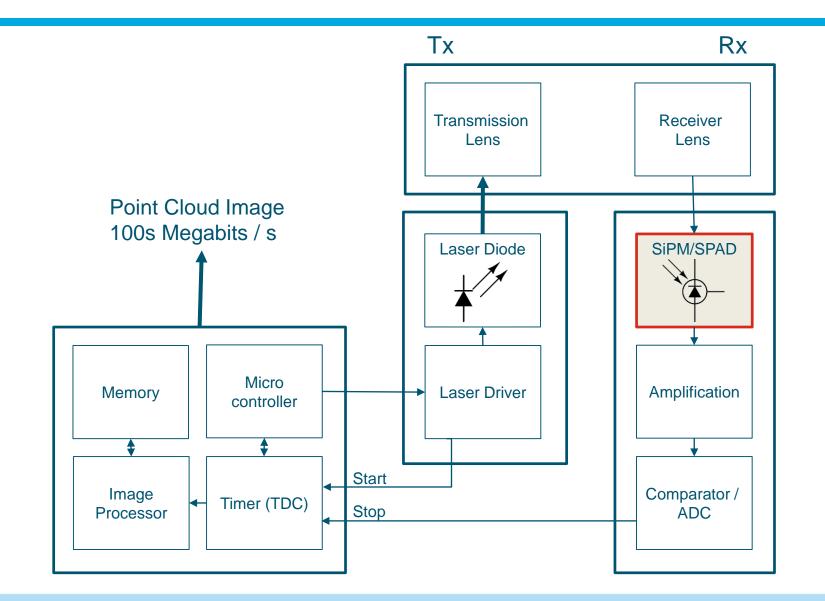
Laser Eye Safety



Maximum Permissible Exposure (MPE) IEC 68025-1 (2014) AoV_x = 0.1° , assumes viewer is 10 cm (4") from laser aperture

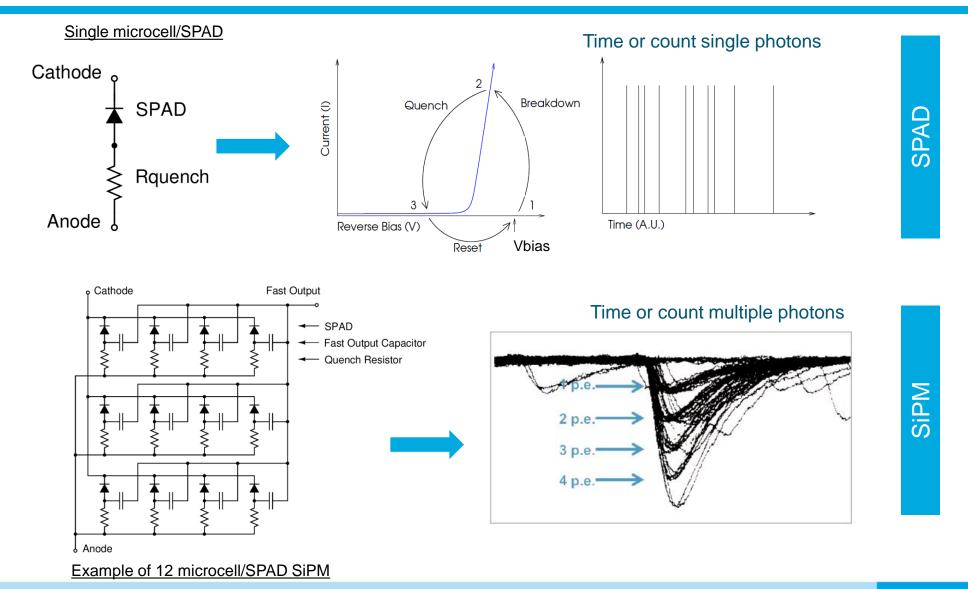


Anatomy of a LiDAR System



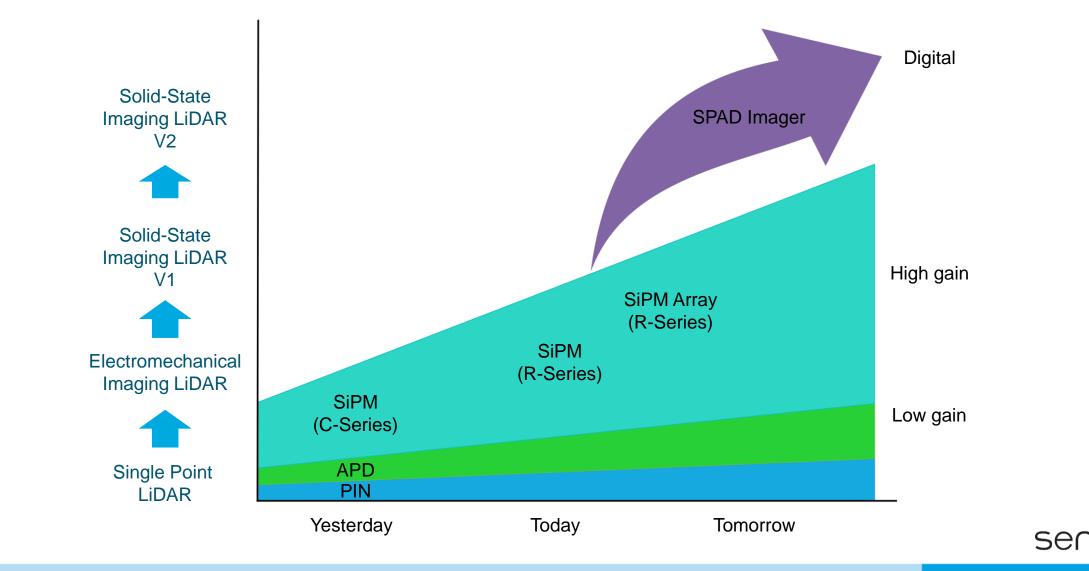


Nomenclature: SPAD and SiPM



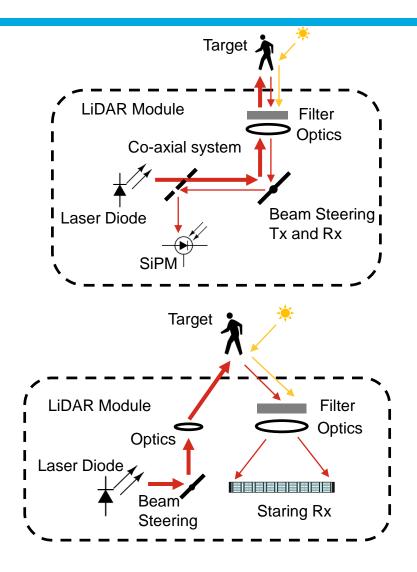
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LiDAR Sensor Technology Evolution



Long-distance LiDAR Systems Evolution

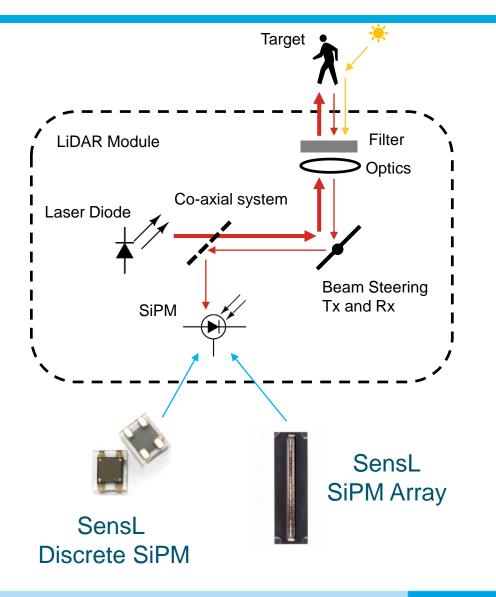
- Today: Electromechanical scanning TX \ RX (coaxial)
 - Single point (2D scan)
 - Single SiPM
 - Vertical/Horizontal line (1D Scan)
 - SiPM array
- Future: Solid-state scanning TX \ Staring RX
 - Single point (2D scan)
 - MEMS mirrors for TX
 - SiPM/SPAD array for RX
 - Vertical/Horizontal line (1D Scan)
 - MEMS mirrors/array for TX
 - SiPM/SPAD array for RX





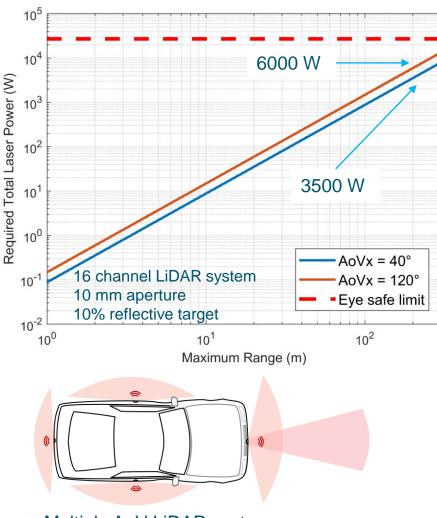
LiDAR Design with SiPM Practical Solutions for Todays LiDAR Modules

- Beam Steering
 - 1D or 2D
 - Electromechanical or MEMS
- Laser Diode
 - High peak power (1000s W)
 - 905 nm commercially available
 - 940 nm solar minimum advantage
 - High pulse rep. rate (100s kHz)
 - Short pulse width (1ns or less)
- Optics
 - Small AoV per pixel
 - Optical bandpass filter (10 to 50 nm)
 - Driven by laser technology
 - Small aperture size
 - For optimal SNR and system size
- SiPM Sensor or SiPM Array
 - High responsivity @ 905 & 940 nm (100kA/W+)
 - High dynamic range
 - Highly uniform (+- 10% output)
 - Low voltage (<50V)



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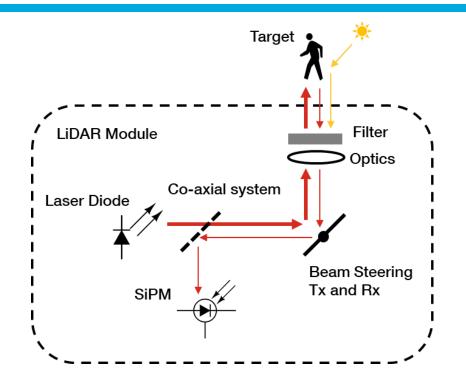
How to Range >200m With SiPM Technology



- Ranging Solution
 - 40° x 30° Long range
 - 120° x 30° Short range
- Sensor Specification
 - 1x16 SiPM
 - R-Series
- Resolution
 - $AoVx = 0.1^{\circ}$
 - AoVy = 1.9°
- Laser Specification
 - 905 nm or 940 nm
 - 1ns laser pulse
 - 500 kHz repetition rate
 - Maintains eye-safety for both systems



Challenges with Today's LiDAR Systems?

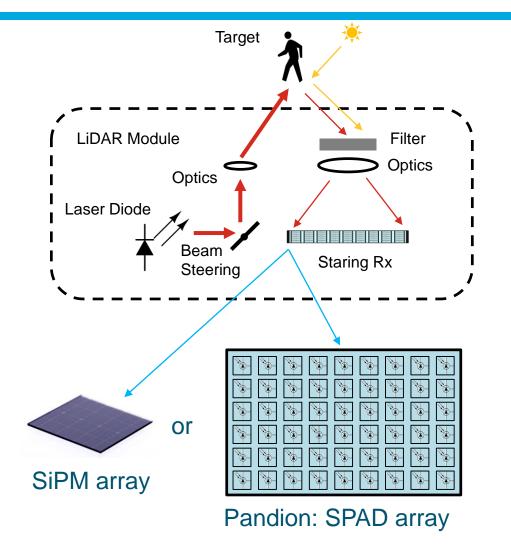


- 1. Poor angular resolution in the y-direction
- 2. Steering the received light onto the sensor



Future LiDAR Design with SPAD or SiPM Arrays

- Beam Steering
 - TX scanner
 - MEMS, optical phase array, other
 - Ultra compact LiDAR solution
 - No RX beam steering required
- Laser Diode
 - High peak power (1000s W)
 - High pulse rep. rate (100s kHz)
 - Short pulse width (1ns or less)
- Optics
 - TX can be miniaturized
 - RX optimized for SPAD or SiPM array
 - Small AoV per pixel

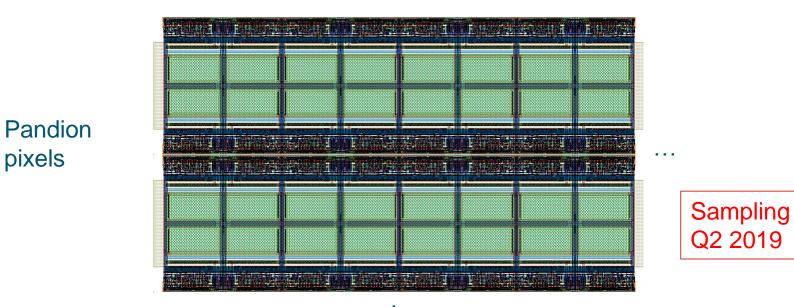




SensL Pandion SPAD Array for Next Generation LiDAR System

- 400×100 SPAD array
- High dynamic range
- High raw data output rate
- Optimised for vertical line scanning
- 0.1° x-y angular resolution

 Suitable for >100m ranging at 10% reflectivity in full sunlight





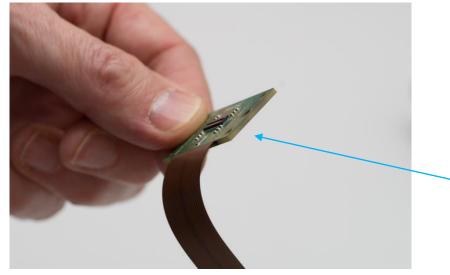
Gen 3 Imaging LiDAR Demonstrator



Anatomy of the Gen 3 Imaging LiDAR System

Parameter	Value
AoV	80° x 5.53°
Pixel AoVx	0.1°
Pixel AoVy	0.325°
Aperture Rx	22 mm
Image Size	800 x 16 pixels
Data Rate	6 Mbits / s
Num. Laser Diodes	16
Pulse Width	1 ns
System Peak Power	400 W (Internal)
System Size	22cm x 18cm x 13cm

Specifications Summary



1x16 SiPM Array on flexible PCB



22 cm

Gen 3 Scanning LiDAR



1x16 Monolithic SiPM Array

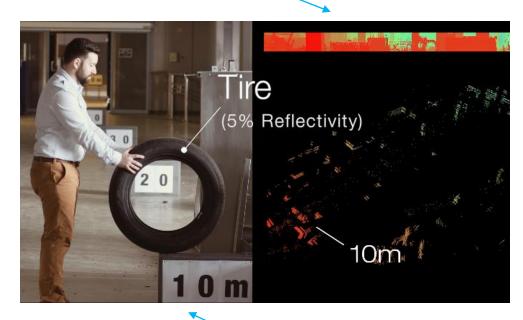


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3D ToF Imaging LiDAR with SiPM Gen3 Demonstration Video

- Demo Objectives:
 - Demonstrate SiPM advantages
 - Long distance low reflective target ranging
 - Imaging
- 1x16 SiPM Array
 - Monolithic SiPM array
 - Compact Rx
- System overview
 - 80° x 5° AoV
 - 16 channels acquired simultaneously
 - Imaging and depth displayed simultaneously

3D ToF Image <



CMOS Camera Image

Full Video Link

https://www.youtube.com/watch?v=Lg2L7v5vb7M



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Thank You

More information can be found at <u>www.sensl.com</u> Contact us at <u>sales@sensl.com</u>