

### A SPAD-Based, Direct Time-of-Flight, 64 Zone, 15fps, Parallel Ranging Device Based on 40nm CMOS SPAD Technology

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- Introduction to ranging device
- Summary of C40SPAD technology platform
- SPAD pixel and array
- SPAD array re-configurability
- SPAD output TDC to histogram
- Histogram processing
  - Range extraction
  - Cross-talk mitigation
  - Dynamic scene adaption



# FlightSense<sup>™</sup> Market Highlights







... making light work

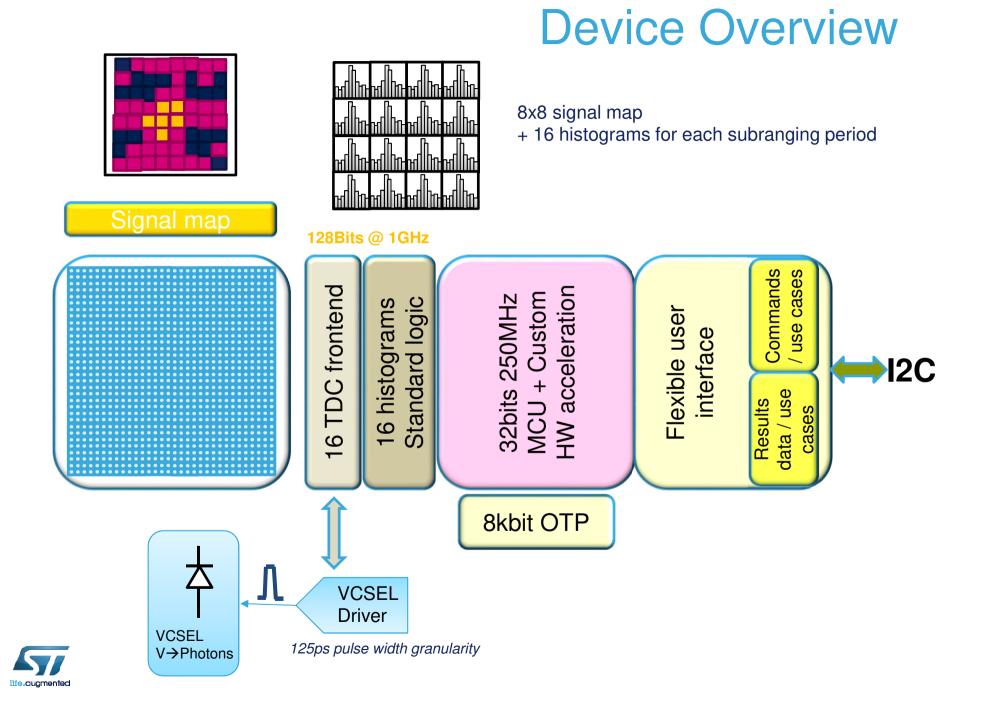






- SPAD based direct time of flight multi-zone parallel device
- Implemented in STMicroelectronics C40SPAD technology
- Capable of 64 zones at 15fps for both signal and distance
- All in one device including on-chip VCSEL driver and in module VCSEL
- 16 parallel full histogram readout channels capable of multiple target detection

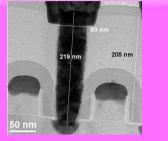


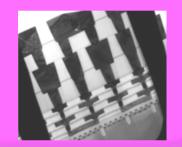


# C040 Technology Platform

#### **40nm CMOS Core Process**

- Dual Gate Oxide
- Single/Dual Vt MOS
- 7 Copper Dual Damascene Metal Levels
- 0.14µm metallization pitch
- Ultra low k dielectrics



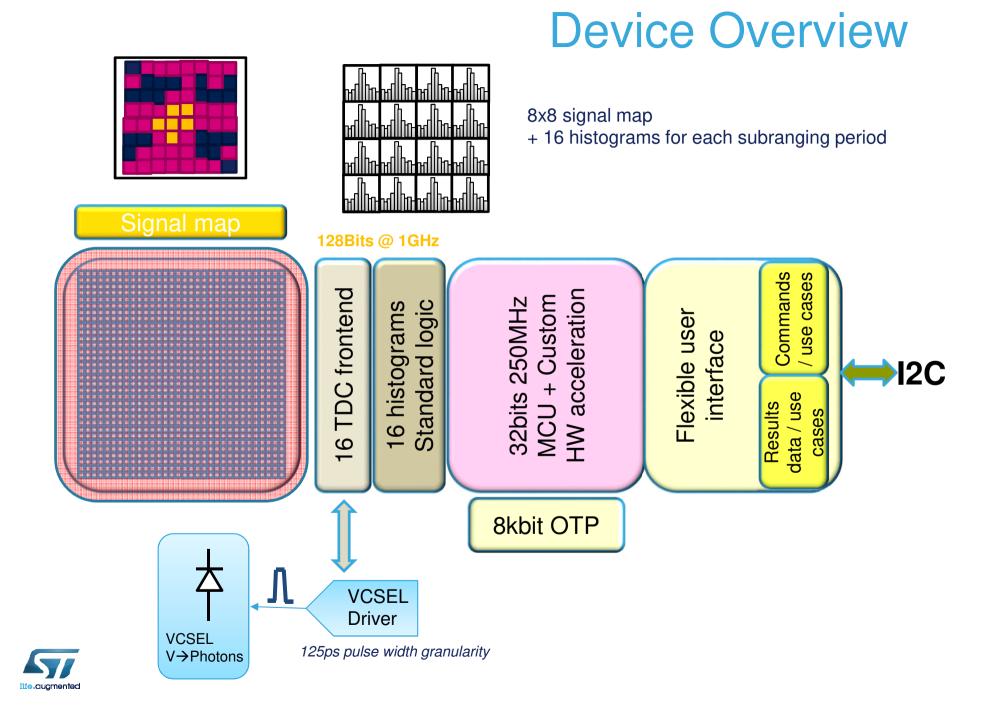


N & P extended Drain MOS Schottky Diode N & P XHPA MOS Natural drift MOS RF MOM Capacitor

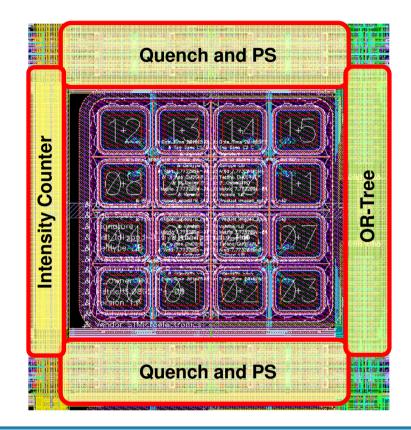
Technology available since 2010 - Source : Crolles 12"

CMOS040\_LP technology is designed for Low Power (1.1V) to serve battery operated and wireless applications. It is a single IO oxide + single core oxide dual-Vt process. It gives access to standard Vt transistors (SVT), low Vt transistors (LVT) & SRAM using LP core oxide and IO transistors. IO transistors (1.8 V or 2.5 V) are using IO oxide (32 or 50A respectively). It uses Copper metallization with 7 metal levels (5 thin + 2 thick) and ultra low-K dielectrics (k=2.55).





### 4x4 Macro-Pixel



- 40% fill factor (with micro-lens)
- Per diode quench circuit and pulse shaper
- OR-tree used to aggregate pixel outputs
- Local intensity counter to monitor per macro-pixel signal rate



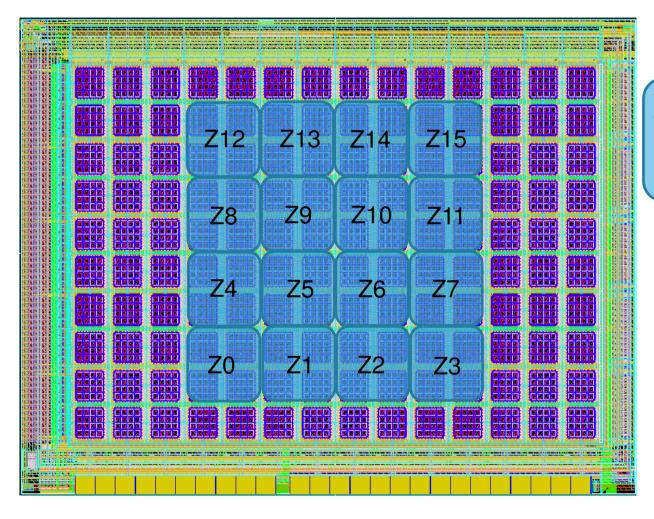
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- 14 x 10 array of macro-pixels
- Each macro-cell features 16
  didoes
- System features 16 parallel readouts from array
- Location and size of each zone is configurable



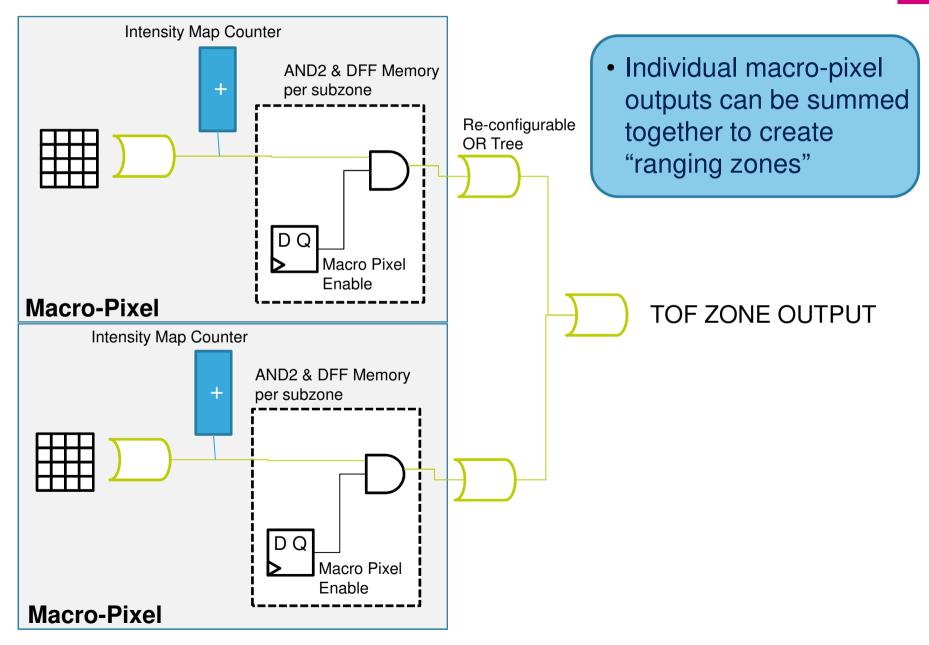


- 16 primary array zones
- In default configuration each zone features 64 SPADs
  - Aggregation of outputs from 4 "macro-pixels"

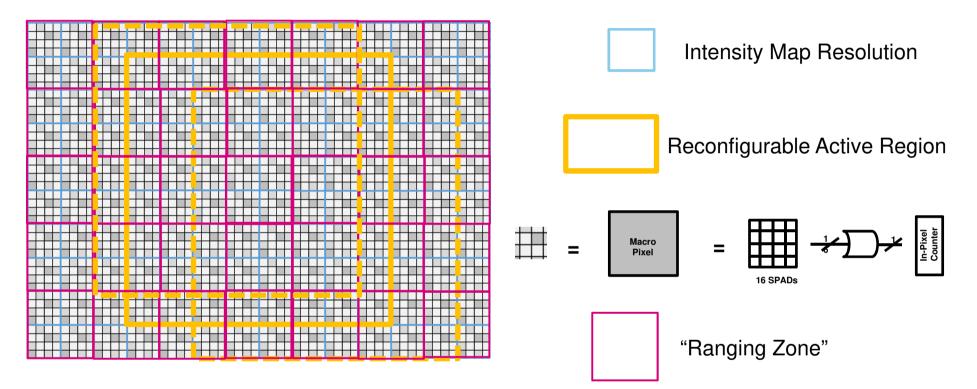


# Macro-Pixel Enable

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# Reconfigurable SPAD Array 14



- The SPAD Array is over-sized to allow active area to be dynamically adjusted.
- Default mode: 4x4 parallel ranging zones with 8x8 signal map (no. of ranging and signal zones can be adjusted to system needs)
- Each ranging zone made up of 2x2 macro pixels (although this is configurable)
- Ranging zone position can be adjusted in X and Y with macro-pixel resolution
- Allows the active array ROI to be adapted to compensate for build tolerances or application needs



### Multi-Zone SPAD Array – Alternative Configurations <sup>15</sup>

						• 5 x 3 zones in
	UNA CONSCIENCS ASS SEEN ENGL SEEN EN					
	710		712	Z14		
SHEE E	Z5	76				
				4	NGGG NG NG	
						5

/9 format



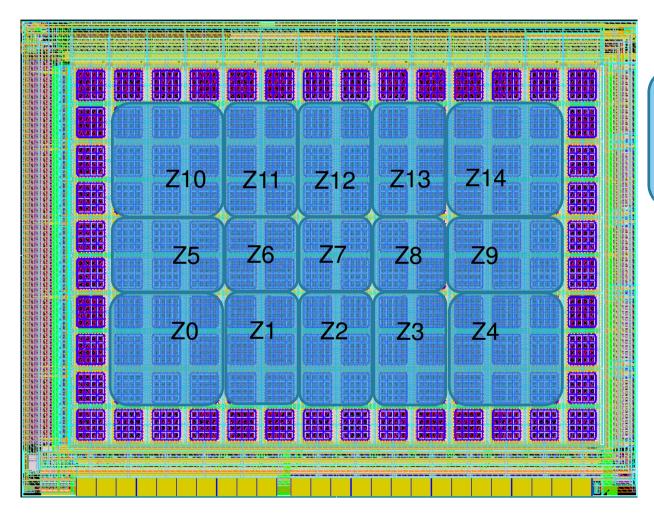
### Multi-Zone SPAD Array – Alternative Configurations

<b>Z</b> 8		Z10	<b>Z</b> 11	
Z0	Z1	22	<b>Z</b> 3	
		ANNE ENER		E CUVE NEU CUVE SECU CUES SEE SCOL SCOL SCOL SCOL SCOL SCOL SCOL SCOL

- 4 x 3 zones in 4/3 format
- SPAD diode resolution zone size



### Multi-Zone SPAD Array – Alternative Configurations



 Over-sizing of peripheral zones to compensate for lens roll-off

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 Possible to have gaps between sub-zones if application requires it



	0268 8525	2925 2352 2029 2029			2029 5252 0527 5252			
		8 8 8 9 8 8 9 8 8 8 8				8889 6333 9883 9883 9883 9883		

 64 zones can be readout over 4 sequential range measurements at a rate of 15fps



Frame 1





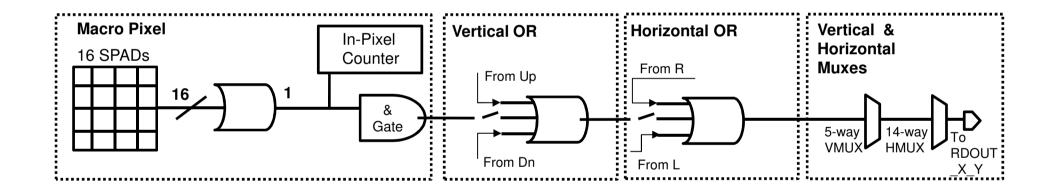
Frame 3



life.ougmented

# Re-Configurable OR Tree 19

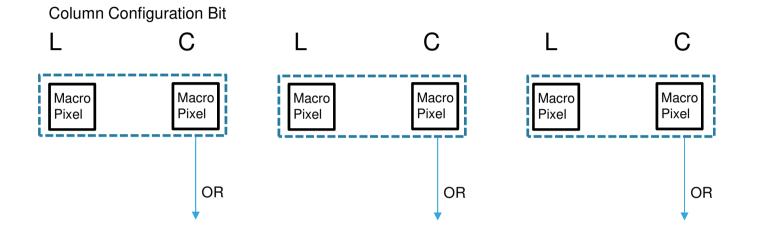
• Three stage re-configurable OR tree:



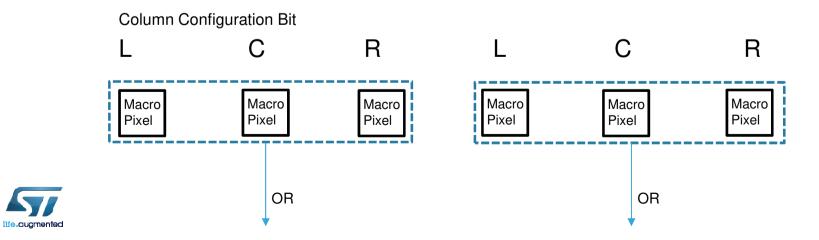


## Re-Configurable OR Cell Combinations 20

#### 2 Macro Pixel OR

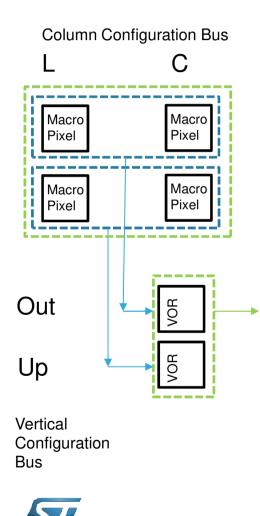


**3 Macro Pixel OR** 



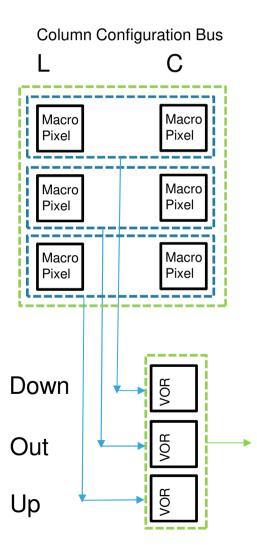
# Re-Configurable OR Cell Combinations 21

#### 2x2 Macro Pixel OR

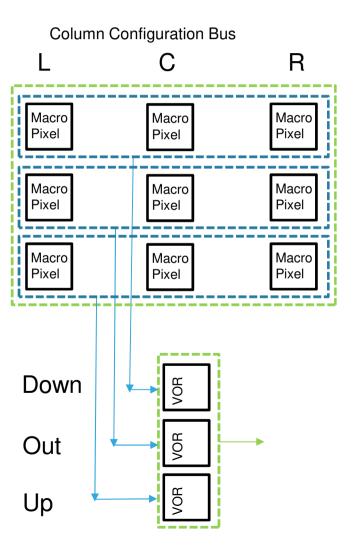


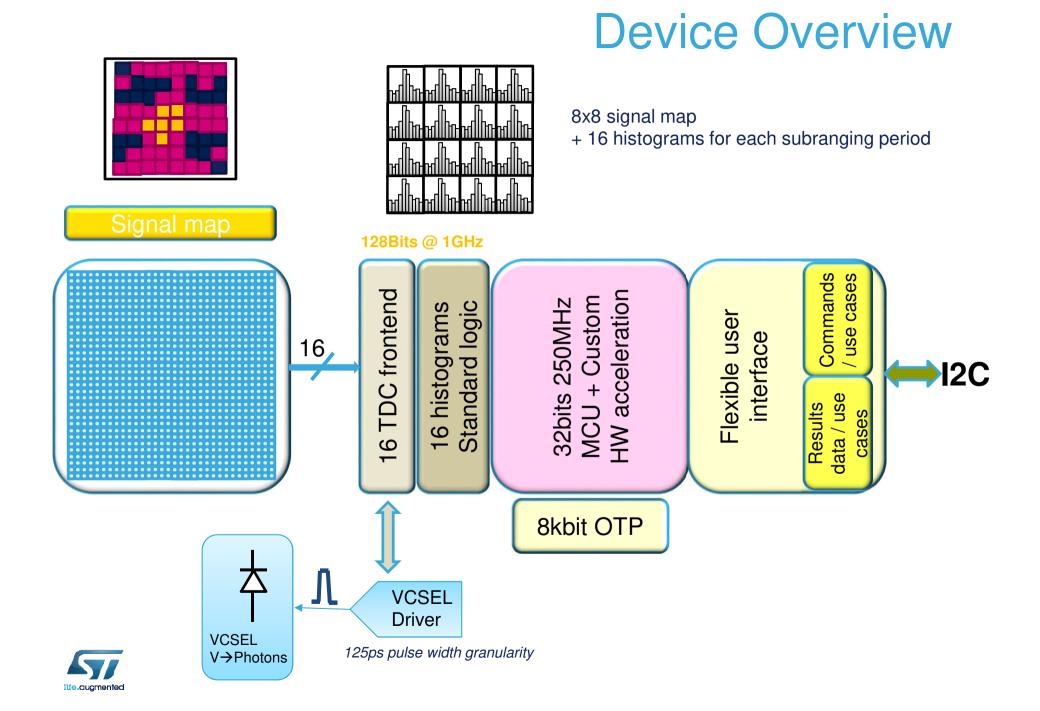
life.augmented

#### 2x3 Macro Pixel OR

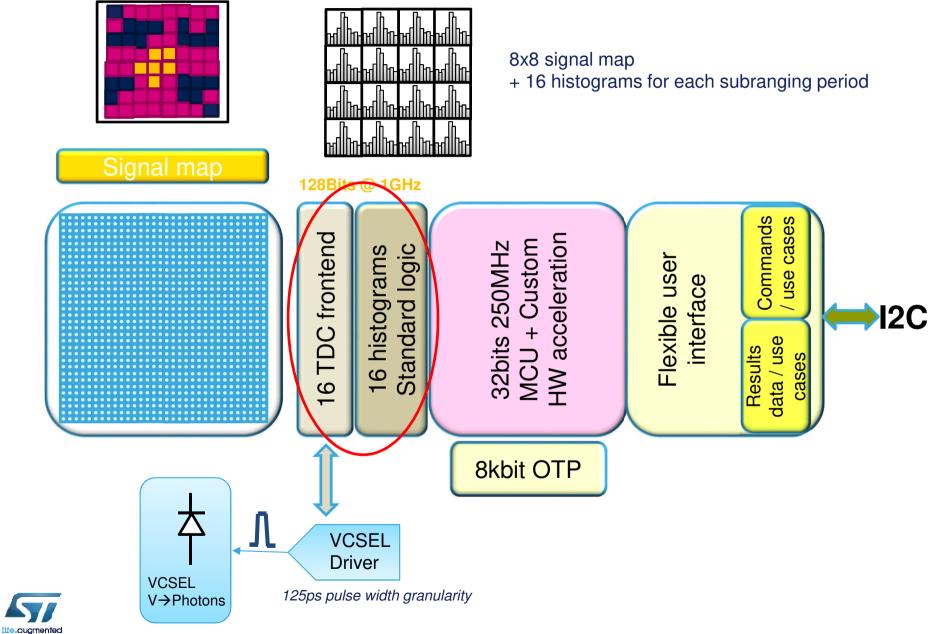


#### 3x3 Macro Pixel OR

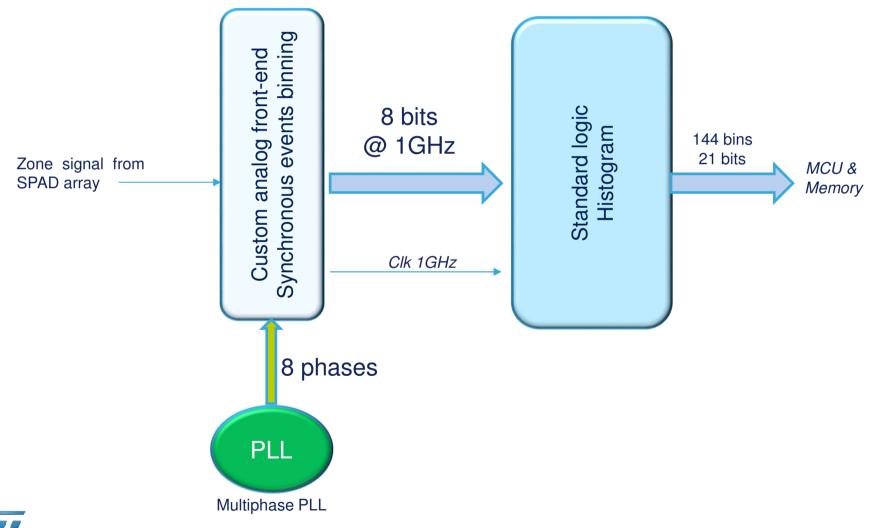




### **Device overview**



### TDC to histograms 24

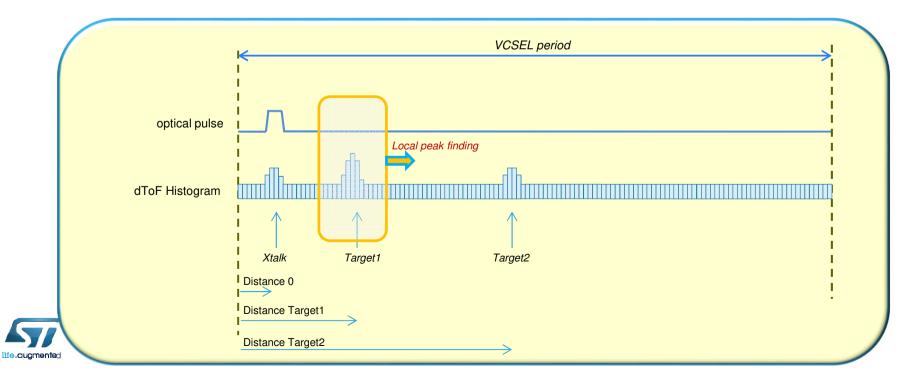




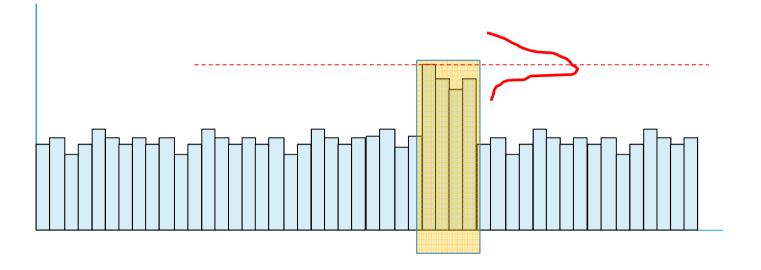
### Direct ToF: Crosstalk & multiple target detection

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- The device is designed to subtract Xtalk peak, and then detect up to 4 targets per histogram
- On-board detection algorithm designed to report leading & falling edge position as well as interpolated median pulse position with **mm** resolution. For each detected target, the MCU is reporting these, as well as confidence level and expected accuracy.



## Adapting laser pulse to each situation 26

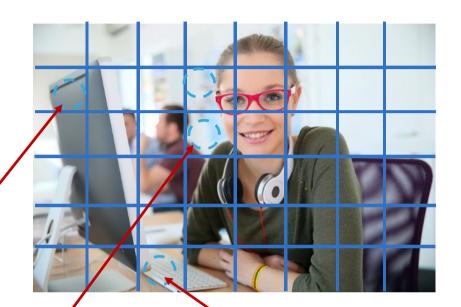


- LONG PULSE allows for low SNR detection (long distance over ambient)
- SHORT PULSE allows for selective close multiple target discrimination



### Scene dynamic range management 27

- One of the challenge in ToF system is the management of the scene dynamic range
  - Low ambient/ High ambient
  - Close / Far target
  - Dark / Bright targets



Close high reflective zone

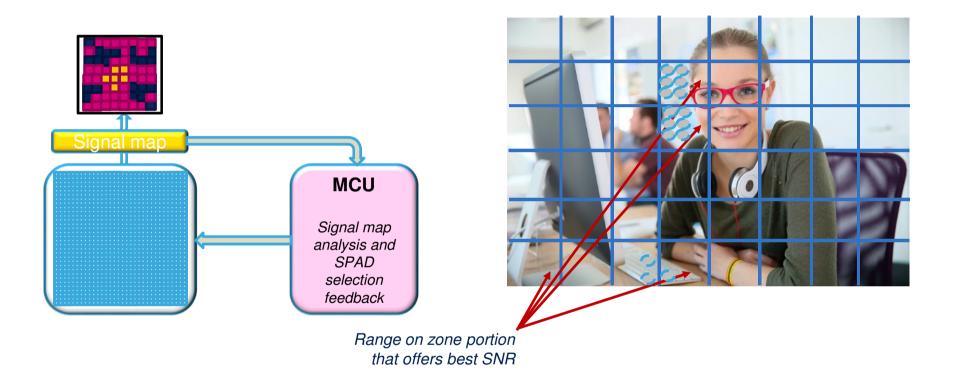
High ambient background

Further darker target

1 880 481 V CSEE Parts 0.0 0.0 0.4



### Scene dynamic range management 28



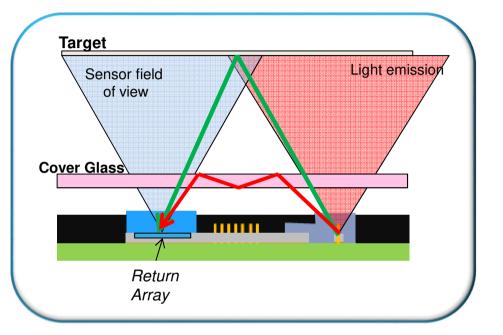
• Thanks to embedded live signal/background map, the device can dynamically assess the SNR for each zone and disable individual SPADs that contribute poorly or negatively to the ranging of the zone

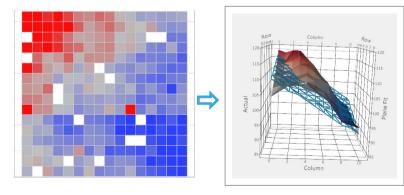


### Dynamic crosstalk management 29

- Crosstalk from cover glass can be significant
- Thanks to histograms, natural immunity exists beyond the point of the emitted pulse width
- But below, at shorter distance, the Xtalk still needs subtracting to not add a ranging offset error to the extracted pulse position
- Moreover, on a larger multizone array, the crosstalk may not be uniform accross.

→ Our device includes a dynamic crosstalk extraction and application taking into account the spatial non uniformity of the crosstalk





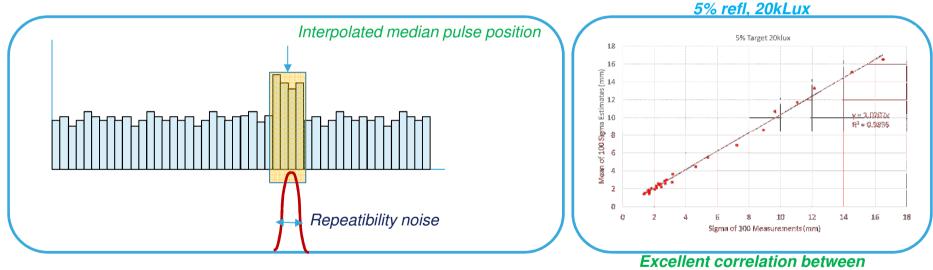
Example of spatial non uniform Xtalk rate



# Noise prediction: sigma estimation

#### Purpose

- Estimates the expected uncertainty given a single range measurement.
- The estimated standard deviation should be equivalent to the measured standard deviation from a large number of measurements (e.g. 100).
- This gives an indication of the repeatability of the measurement reported by the device.
- The sigma estimator is intended for reporting range quality.



estimator and measured

For each target reported, the device takes into account the ambient, signal and crosstalk rate, as well as pulse width, in order to accurately estimate the noise associated with this target.



This is easing considerably the job of the user to estimate the confidence of the reported data

### **Device overview**

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Wide Angle Parallel Multi-zone detection

### **Highlights**

- All-in-one compact lensed module
  - Class 1 certified 940nm invisible VCSEL
  - 61° FoV

0

- ToF processing on embedded 32bit MCU
- Target specification
  - Functional under 100klux daylight & direct light
  - 8x8 15fps operation mode
  - Cover glass xtalk calibration free
  - Zero lag Region of Interest reporting
- Power modes
  - Fully autonomous 1.4mW Presence detection
  - Smart power management based on ambient light level
- Spatial scene understanding
  - Multiple object detection
  - Cover glass xtalk immune & dynamic subtraction







### Conclusions 32

- A SPAD-Based, Direct Time-of-Flight, 64 Zone, 15fps, Parallel Ranging Device Based on 40nm CMOS SPAD Technology
- A SPAD-based, direct TOF device is presented
- Up to 64 independent range measurements across FoV can be made
- Zone position and size configurable
- 16-channel histogram processing
- Histogram processing includes
  - Range and signal rate extraction
  - Cross-talk removal
  - Dynamic signal rate management



# Acknowledgements 33

#### • ST Imaging Division

- Edinburgh and Grenoble silicon and module design teams
- Architecture Team
- Applications

